

§6.5 Least Squares Problems

Motivation: If A is an $m \times n$ matrix and b a vector in \mathbb{R}^m , sometimes the matrix equation $Ax = b$ is inconsistent, i.e. has no solution.

Even though there is no solution, can we find a vector \hat{x} in \mathbb{R}^n such that $A\hat{x} \approx b$.
In other words, can we find a best approximation?

We aim to make the error $b - Ax$ as small as possible.

Definition

With the notation as above, we say \hat{x} is a least-squares solution of $Ax = b$ if

$$\|b - A\hat{x}\| \leq \|b - Ax\|$$

for all x in \mathbb{R}^n .

How can we find such an \hat{x} ?

We must find an \hat{x} so that $A\hat{x}$ is as close to b as possible. We can use orthogonal projections!

Recall Ax is a vector in $\text{Col } A$ for any x and $Ax=b$ has a solution if and only if b is in $\text{Col } A$.

If b is not in $\text{Col } A$, let's find the closest vector \hat{b} in $\text{Col } A$ to b . By the best approximation theorem (§6.3), we have

$$\hat{b} = \text{proj}_{\text{Col } A} b$$

With this $Ax = \hat{b}$ is consistent and hence has a solution \hat{x} such that

$$A\hat{x} = \hat{b}.$$

This \hat{x} is exactly what we want, but could be difficult to find.

(unless we come up with a good process)

Write a_1, \dots, a_n for the columns of A and suppose $A\hat{x} = \hat{b}$ where $\hat{b} = \text{proj}_{\text{Col}A} b$. By the orthogonal decomposition theorem, recall $b - \hat{b}$ is orthogonal to $\text{Col}A$, thus

$$0 = a_i \cdot (b - \hat{b}) = a_i \cdot (b - A\hat{x})$$

for all $i = 1, \dots, n$. Recall from the definition of \cdot product ($u \cdot v = u^T v$) this means

$$a_i^T (b - A\hat{x}) = 0 \quad \text{hence} \quad A^T (b - A\hat{x}) = 0$$

since a_i^T is a row of A^T for $i = 1, \dots, n$.

Rearranging, we see

$$A^T b - A^T A x = 0 \implies A^T A \hat{x} = A^T b$$

Thus it suffices to find the solution(s) to

$$A^T A x = A^T b$$

We call the equations of $A^T A x = A^T b$ the normal equations for $Ax = b$

Example

Find a least squares solution to $Ax = b$
where

$$A = \begin{bmatrix} -1 & 4 \\ 2 & -3 \\ -1 & 3 \end{bmatrix} \quad b = \begin{bmatrix} 12 \\ 6 \\ 6 \end{bmatrix}$$

Solution:

$$A^T A x = A^T b$$

$$\begin{bmatrix} -1 & 2 & -1 \\ 4 & -3 & 3 \end{bmatrix} \begin{bmatrix} -1 & 4 \\ 2 & -3 \\ -1 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -1 & 2 & -1 \\ 4 & -3 & 3 \end{bmatrix} \begin{bmatrix} 12 \\ 6 \\ 6 \end{bmatrix}$$

$$\begin{bmatrix} 6 & -13 \\ -13 & 34 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -6 \\ 48 \end{bmatrix}$$

$$\left[\begin{array}{cc|c} 6 & -13 & -6 \\ -13 & 34 & 48 \end{array} \right] \sim \left[\begin{array}{cc|c} 1 & -13/6 & -1 \\ 0 & 35/6 & 35 \end{array} \right] \sim \left[\begin{array}{cc|c} 1 & -13/6 & -1 \\ 0 & 1 & 6 \end{array} \right]$$

$$\sim \left[\begin{array}{cc|c} 1 & 0 & 12 \\ 0 & 1 & 6 \end{array} \right]$$

Thus $\hat{x} = \begin{bmatrix} 12 \\ 6 \end{bmatrix}$ is a least squares solution.

Remark

$A^T A x = A^T b$ is consistent, but this doesn't mean there's always one unique solution. Depending on free variables, sometimes there are infinitely many least squares solutions.

Example

Find all least squares solutions to $Ax = b$

where

$$A = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \\ 1 & 1 & 0 \end{bmatrix}$$

$$b = \begin{bmatrix} 5 \\ 3 \\ 1 \\ 1 \end{bmatrix}$$

solution:

$$A^T A x = A^T b$$

$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 1 & 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \text{---} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 1 & 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 5 \\ 3 \\ 1 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 4 & 2 & 2 \\ 2 & 2 & 0 \\ 2 & 0 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 10 \\ 2 \\ 8 \end{bmatrix}$$

$$\begin{bmatrix} 4 & 2 & 2 & | & 10 \\ 2 & 2 & 0 & | & 2 \\ 2 & 0 & 2 & | & 8 \end{bmatrix} \sim \begin{bmatrix} 1 & \frac{1}{2} & \frac{1}{2} & | & \frac{5}{2} \\ 0 & 1 & -1 & | & -3 \\ 0 & -1 & 1 & | & 3 \end{bmatrix} \sim \begin{bmatrix} 1 & \frac{1}{2} & \frac{1}{2} & | & \frac{5}{2} \\ 0 & 1 & -1 & | & -3 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

pivots

x_3 free!

$$\begin{cases} x_1 + \frac{1}{2}x_3 = 4 \\ x_2 - x_3 = -3 \end{cases}$$

$$\sim \begin{bmatrix} 1 & 0 & 1 & | & 4 \\ 0 & 1 & -1 & | & -3 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

$$\hookrightarrow \begin{cases} x_1 = 4 - x_3 \\ x_2 = -3 + x_3 \\ x_3 = x_3 \end{cases}$$

$$\hat{X} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 4 \\ -3 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$$

Thus \hat{X} is a least squares solution for any value of x_3 .

Theorem

Let A be an $m \times n$ matrix. The following are equivalent:

- 1) $Ax = b$ has a unique least squares solution \hat{x} for all b in \mathbb{R}^m
- 2) The columns of A are linearly independent
- 3) $A^T A$ is invertible.

Proof

(1) \Rightarrow (2): Suppose $Ax = b$ has a unique least squares solution for all b . Pick $b = 0$ so $Ax = 0$ has a unique least squares solution. Thus

$$A^T A x = A^T \cdot 0 = 0$$

has a unique solution. Obviously $x = 0$ is a solution so it must be the unique solution. Thus we've shown if $Ax = 0$, then $x = 0$. Thus $\text{Null } A = 0$ which implies the columns of A are linearly independent.

(2) \Rightarrow (3): Suppose the columns of A are linearly independent. Then $Ax=0$ has only the trivial solution $x=0$.

Since $A^T A$ is a square matrix, $A^T A$ is invertible if and only if $A^T A x = 0$ has only the trivial solution $x=0$.

If $A^T A x = 0$, then

$$0 = x^T \underbrace{(A^T A x)}_{=0} = x^T A^T A x = (Ax)^T (Ax) = Ax \cdot Ax$$

by the definition of \cdot product. Now $Ax \cdot Ax = 0$ implies $Ax=0$, hence $x=0$ (linear independent columns). Thus $A^T A x = 0$ has only the trivial solution so $A^T A$ is invertible.

(3) \Rightarrow (1): Suppose $A^T A$ is invertible and consider the matrix equation $Ax=b$. ~~And~~ ~~is~~ A least squares solution to $Ax=b$ is a solution to

$$A^T A x = A^T b$$

if $A^T A$ is invertible, then $\hat{x} = (A^T A)^{-1} A^T b$ is the unique least squares solution.

Theorem

Suppose A is an $m \times n$ matrix with linearly independent columns. Write $A = QR$ with Q and R as in §6.4

From the previous theorem $Ax = b$ has a unique least squares solution (columns are linearly independent). Moreover this solution is

$$\hat{x} = R^{-1}Q^T b$$

Proof

We need only show $A\hat{x} = \hat{b}$ where \hat{x} is as above.

$$A(R^{-1}Q^T b) = (QR)(R^{-1}Q^T b) = QR R^{-1}Q^T b = QQ^T b$$

Since the columns of Q are an orthonormal basis of $\text{col } A$, by the last theorem of §6.3

$$QQ^T b = \text{proj}_{\text{col } A} b = \hat{b}$$